# THE UNIVERSITY of TENNESSEE

# MOTOR LEARNING STRATEGIES INCREASE INTRINSIC MOTIVATION AND QUADRICEPS TORQUE OUTPUT IN HEALTHY INDIVIDUALS

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## The authors have no conflicts of interest and nothing to disclose.

# Introduction - The Problem

- Secondary ACL injury rates of either the same or contralateral leg are reported as high as 33%.<sup>1</sup>
  - This percentage is believed to be caused by returning to sport too quickly<sup>1</sup> as well as poor quadriceps re-education and neuromuscular control.<sup>2</sup>
- □ There is an estimate of 43% of patients that suffered an ACL injury that were also diagnosed with early-onset osteoarthritis (OA) within 10 years.<sup>3</sup>
- Deficient quadriceps function is associated with post-traumatic earlyonset OA.<sup>3</sup>
- Poor functional performance at one year following ACL-R can be associated with risk of OA.<sup>4</sup>

# Introduction - The Solution

- One of the barriers of RTP following ACL-R is quadricep function deficits in quadriceps torque production.<sup>5</sup>
  - This leads to decreased somatosensory processing<sup>6</sup> and efferent motor drive impairments.<sup>7</sup>
- Current rehabilitation has been lacking in the realm of motor learning principles and strategies that could potentially improve both physical and psychological outcomes in ACL-R patients.<sup>8</sup>
- Motivation is a broad term that describes behavior in components of energy, direction, and intensity.<sup>9</sup>
  - Is a component of motor learning for its environmental impact on motor behavior.<sup>9</sup>
  - Feedback is thought to play a large role in motor learning and motivational increases because it allows the learner to see their performances during a certain task.<sup>9,10</sup>

# Introduction

#### OPTIMAL Theory<sup>9</sup>

- **Optimizing Performance Through Intrinsic Motivation and Attention for Learning**
- Motivation component consists of autonomy support and enhanced expectancies.<sup>9</sup>
  - Motivation can predict sport injury and rehabilitation outcomes.<sup>11</sup>
  - Patient autonomy allows for greater motivation and patient engagement during motor tasks.<sup>9,11,12,13</sup>
- Attentional component looks at the impact of external foci.<sup>9</sup>
  - External foci can be used to increase or enhance performance as well as the learning of motor skills.<sup>12,14</sup>



Wulf G, Lewthwaite R, 2016

# Purpose & Hypothesis

Compared with a standard of care assessment, incorporating motor learning strategies will improve intrinsic motivation and peak quadriceps torque output in a young, healthy, asymptomatic population.

# Study Design

We employed a within-subject to treatment crossover design.

- ie. Participant #1 completes Control, Experimental so
  Participant #2 completes Experimental, Control
- Participants only used their dominant leg which was defined as their kicking leg.
- Independent variables
  - Control (Non-Optimized)
  - Experimental (Optimized)
- Dependent variables
  - Interest/enjoyment
  - Peak torque



# Participants

- □ Demographics:
  - ☑ N = 33
  - P Age: 23.45±3.62 years
  - Beight: 172.12±8.31 cm
  - Mass: 77.80±12.71 kg
  - 24 females, 9 males

Inclusion criteria:
 At least 18 years old

Exclusion criteria:
 History of ACL-R within 2 years
 Over 35 years old

# Methods - Dynamometer

- 2 counterbalanced conditions:
  - Non-Optimized (control)
  - Optimized (experimental)
- Tested dominant kicking leg
- Kick out (isometric quadricep extension) at 45° knee flexion, 3x5 seconds with a 30 second rest period between each rep
  - Completed twice: one with the Optimized condition and one with the Non-Optimized condition

# Methods - Motivation & Attention

- Control Non-Optimized
  - No motor learning manipulation
  - Participant was not able to see the screen
  - "Kick your leg as hard as you can"

- Experimental Optimized
  - Allowed selection of bar or line graph
  - Watching the screen during your reps has been shown to increase your quadriceps force production"



# Methods - Motivation & Attention - IMI

### □ Intrinsic Motivation Inventory (IMI)

- 7-item Interest/Enjoyment Subscale was used
- Participant was asked to complete the survey after each condition rating the truth of each statement.
  - 1- not at all true
  - 7- very true

#### Interest/Enjoyment

I enjoyed doing this activity very much This activity was fun to do. I thought this was a boring activity. (R) This activity did not hold my attention at all.(R) I would describe this activity as very interesting. I thought this activity was quite enjoyable. While I was doing this activity, I was thinking about how much I enjoyed it.

McAuley E et al, 1989

# Data Handling

Primary Outcome Variables

- Peak quad torque normalized to body mass (Nm/kg)
  - Absolute peak torque as computed by the Biodex
- Intrinsic Motivation
  - Interest/enjoyment subscale of intrinsic motivation inventory survey
  - Higher score meant higher interest/enjoyment

□ Data were inspected for normality via histograms and outliers were removed.

- Paired samples t-tests were conducted for peak quadriceps torque and intrinsic motivation. The differences were correlated and graphed.
- □ A linear multiple regression was conducted to determine the extent to which increases in motivation explained variance in Optimized peak torque.
- A path model was conducted to determine potential mediation effects of intrinsic motivation on changes in peak quadriceps torque.

□ JASP 0.19.3 was used for all analyses

# **Results-Normality**

## Missing data

Two subjects were lacking motivation data and one subject missed a rep for Non-Optimized torque data, which was computed manually.



Control Peak Torque

**Experimental Peak Torque** 

# **Results–Increases in Torque and Motivation**

Peak torque increased between Non-Optimized and Optimized conditions (p < .01, Cohen's *d* = 0.57) Motivation increased between Non-Optimized and Optimized conditions (p = .01, Cohen's *d* = .53) Differences in motivation and peak torque were minimally negatively correlated (r = -0.16)

r = -0.163



**Difference in Motivation** 

# **Results–Linear Regression**

#### Baseline Conditions

- Non-Optimized peak torque predicted 87% of the variance in Optimized peak torque (p < .001).</li>
- Non-Optimized interest/enjoyment explained an additional 0.8% (R<sup>2</sup> change *p*=.32)
- Addition of Motivation
  - The addition of Optimized interest/enjoyment an additional 2.4% (R<sup>2</sup> change *p*=.07)

Model	R	R <sup>2</sup>	Adjusted R <sup>2</sup>	RMSE	R² Change	df1	df2	р
Mo	0.000	0.000	0.000	0.601	0.000	0	18	
M1	0.933	0.871	0.864	0.222	0.871	1	17	< .001
M <sub>2</sub>	0.938	0.879	0.864	0.222	0.008	1	16	0.323
M <sub>3</sub>	0.950	0.903	0.884	0.205	0.024	1	15	0.073

Model Summary – Pk\_Trq\_E\_Norm\_Nm/kg

# **Results-Potential Mediation**



 Baseline peak torque was a strong indicator of how much motivation would change.
 Changes in motivation did not transfer over to final experimental peak torque.



□ We observed moderate effects of the intervention for both the IMI-survey (Cohen's *d* of 0.53) and peak torque (Cohen's *d* of 0.57).

Increases in motivation minimally correlates with decreases in peak torque (r = -0.16).

Non-Optimized peak torque strongly correlates with increases in motivation, but increases in motivation do not translate to greater Optimized peak torque.

# Discussion

## The manipulation worked but the mechanism is still unknown

- Could be the ordering of the manipulation (crossover study design or washout)
- Could be a missing variable that we are not considering:
  - Floor effects (the stronger someone is at baseline, the more likely someone is to increase their motivation (r = .12))
  - Using different surveys to look at individual learning strategies or other trait characteristics
    - Determination
    - Grit
    - Kinesthetic learning
    - Visual learning
    - Auditory learning

# Limitations & Constraints

## Limitations

- Ricking early
- Fatigue during second round
- Effort
- Constraints
  - I Learning effect
    - Use of a longer washout period
    - Mixed effect model (fixed and random)

# **Clinical Relevance**

- Improved quadricep function
  Greater likelihood of RTS<sup>4</sup>
- Optimization of patient autonomy
  Increased patient self-efficacy<sup>9</sup>
- Mitigate risk of injury/re-injury<sup>4</sup>
  Improved biomechanics<sup>12</sup>
- Patient-centered care approach
  - Inclusion of motivation based rehabilitation<sup>9,12</sup>



# **Future directions**

- Using different surveys to look at individual learning styles in order to determine the mechanism
- Multisession study to determine retention effects
- Transfer of quadricep function to other tasks (e.g., jumping)
- Confirm if these results hold in a pathological population

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